## "TRADER" SERVICE SHEET

MPLOYING a ferrite-rod type internal aerial, the Pilot BM90 is a 4-valve (plus metal rectifier) portable superhet designed to operate from all-dry batteries or A.C./D.C. mains of 110V and 200-250V, 40-100 c/s in the case of A.C. The waveband ranges are 185-550m and 1,200-2,000m.

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Release date and original price: June, 1954 £13 19s 9d. Purchase tax extra.

	CAPACITORS	Values	Loca- tions
C1	V1 C.G	100pF	F3
C2	1 1st I.F. trans. tun- f	$100 \mathrm{pF}$	B1
C3	} ing {	100pF	B1
C4	A.G.C. decoupling	$0.01 \mu F$	F3
C5	V1 osc. C.G	$100 \mathrm{pF}$	F3
C6	L.W. osc. trim,	450pF	F3
C7.	Osc. tracker	630pF	G3
C8	Osc. reaction coup.	$0.01 \mu F$	F3
C9	V2 S.G. decoup	$0.01 \mu F$	E3
C10	2nd I.F. trans. tun- f	$100 \mathrm{pF}$	B1
C11	} ing {	100pF	B1
C12	Filament decoup.	$0.1 \mu F$	D2
C13	I F by pages	$100 \mathrm{pF}$	E3
C14	} I.F. by-passes {	$100 \mathrm{pF}$	E2
C15	A.F. coupling	$0.01 \mu F$	<b>E</b> 3
C16*	H.T. decoupling	$8\mu F$	B1
C17 -	V3 S.G. decoupling	$0.04 \mu F$	E3
C18	I.F. by-pass	220pF	E3
C19	A.F. coupling	$0.01 \mu F$	<b>E</b> 3
C20	Tone corrector	$0.002 \mu F$	-
C21*	Filament smoothing	$250 \mu F$	D3
C22*	TT amouthing	$32\mu F$	B1
C23*	H.T. smoothing {	$32\mu F$	B1
C24	Mains R.F. by-pass	$0.05 \mu F$	G3
C25‡	L.W. aerial trim	120pF	G3
C26‡	M.W. aerial trim	60pF	G3
C27†	Aerial tuning		A1
C28†	Oscillator tuning		A1
C29‡	M.W. osc. trim	60 pF	<b>F</b> 3
C30‡	L.W. osc. trim	$120 \mathrm{pF}$	G3

# PILOT BM90

A.C./D.C. All-dry Portable

	RESISTORS	Values	Locations
R1 R2 R3 R4 R5 R6 R7 R8 R9 R10 R11 R12 R13 R14 R15 R16 R17 R18	V1 C.G. V1 osc. C.G. V1 osc. C.G. V1 filament shunt V1 S.G. feed V2 S.G. feed V2 S.G. feed V2 S.G. feed V3 S.G. feed V4 S.G. decoupling LF, stopper Volume control V3 C.G. V3 filament shunt H.T. decoupling V3 ande load V3 S.G. feed Neg. feed-back V4 C.G. V4 filament shunt Filament shunt Filament shunt	3-3MΩ 100kΩ 180Ω 10kΩ 47kΩ 220Ω 2-2MΩ 47kΩ 1MΩ 4-7MΩ 1MΩ 4-7MΩ 1MΩ 4-7MΩ 10MΩ 4-7MΩ 10MΩ 4-7MΩ 10MΩ 4-7MΩ 10MΩ 4-7MΩ 10MΩ	
R19 R20 R21 R22	$ \begin{cases} \text{H.T.} & \text{smoothing} \\ \text{and} & \text{voltage} & \text{adj.} \\ \text{V4 G.B.} & \dots & \dots \end{cases} $	$^{400\Omega}_{2,370\Omega}_{380\Omega}_{220\Omega}$	C1 C1 C1 D3

отн	ER COMPONENTS	Approx. Values (ohms)	Loca- tions
L1 L2 L3 L4 L5 L6 L7 L8 L9	Strict Speech coll  Sinternal aerial colls  Osc. tuning coll Osc. reaction coil  Str.F. trans. { Pri. Sec. Speech coll (Pri. Sec.	3·8 1·2 2·3 1·0 10·0 10·0 10·0 2·5 480·0	C1 B1 F2 F2 B1 B1 B1
T1 S1-S3 S4(B)- S10(B)	O.P. trans. {Pri. Sec. Waveband switches Mains/battery sw.	_	B1



Appearance of the Pilot BM90.

### CIRCUIT DESCRIPTION

The aerial input coils L1 (L.W.) and L2 (M.W.) are mounted on opposite ends of a length of ferrite rod to form the internal aerial, and are tuned by C27. S1 closes to short-circuit L1 for M.W. operation.

Heptode valve (VI, Brimar 1R5) operates as frequency changer with electron coupling. Oscillator grid coil L3 is tuned by C28 for both M.W. and L.W. operation. Parallel trimming by C29 (M.W.) and C6, C29, C30 (L.W.); series tracking on both bands by C7. Reaction coupling from oscillator anode via L4 and the common impedance of C7.

Second valve (V2, Brimar 1T4) is a variable mu R.F. pentode operating as intermediate frequency amplifier with tuned transformer couplings C2, L5, L6, C3 and C10, L7, L8, C11.

Intermediate frequency 470 ke/s.

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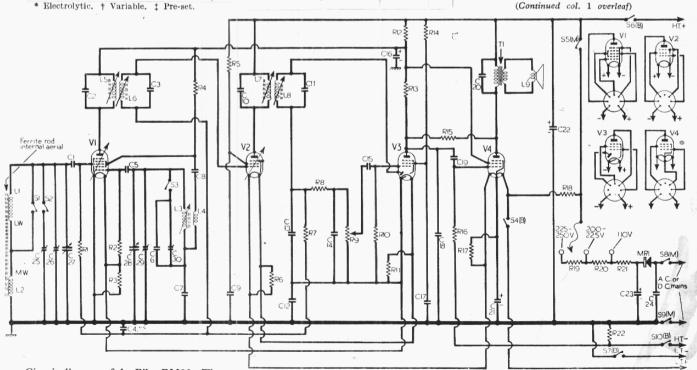
Diode signal detector is part of diode pentode valve (V3, Brimar 185). Audio frequency component in its rectified output is developed across volume control R9, which operates as diode load, and is passed via C15 to pentode section.

I.F. filtering by C13, R8, C14.

D.C. potential developed across R8, R9 is fed back as bias to V1 and V2, giving automatic gain control.

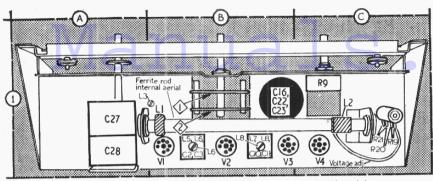
Resistance canacitance coupling via R13, C19.

Resistance-capacitance coupling via R13, C19 and R16 between V3 and pentode output valve (Continued col. 1 overleaf)



Circuit diagram of the Pilot BM90. The mains/battery switches bear the suffix (M) or (B) to indicate that they close for mains or battery operation respectively.





Plan view of the chassis showing the ferrite-rod internal aerial.

#### Circuit Description-continued.

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(V4, Brimar 3V4). Tone correction by C20 in V4 anode circuit and by negative feed-back between the anodes of V4 and V3 via R15.

For battery operation, power supplies are carried by mains/battery switches S4(B), S6(B), S10(B), which close in that position as indicated by the suffix (B). For mains operation S5(M), S8(M) and S9(M) close. In the "off" position all the switches open.

Mains H.T. current is supplied by metal rectifier (MR1, Westalite 18RA) which is cooled by surface contact with the chassis and dispenses with the normal cooling fins. Smoothing by R19, R20, R21, which are also used for voltage adjustment, and electrolytic capacitors C22, C23. Filament current for mains operation is taken from the H.T. circuit via R18.

The filaments are series-connected for both mains and battery operation. Blas is obtained from the appropriate points in the filament chain. For the purpose of battery economy the bias applied to V4 is supplemented by the voltage dropped across R22 in the H.T. negative lead to chassis. R3, R6, R11 and R17 by-pass the H.T. current from the valves past the filaments.

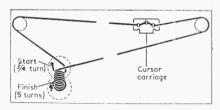
#### CIRCUIT ALIGNMENT

1.F. Stages.—In order to make the underchassis 1.F. adjustments accessible the chassis should be withdrawn from its carrying case. Switch receiver to M.W. and turn gang to maximum. Connect output of signal generator, via an  $0.1\mu\mathrm{F}$  capacitor in each lead, to control grid (pin 6) of V1 and chassis. Feed in a 470 kc/s (638.3m) signal and adjust the cores of L8 (location reference B1), L7 (E3), L6 (B1) and L5 (F3) for maximum output. R.F. and Oscillator Stages.—Replace chassis in carrying case. Transfer signal generator leads to a loop consisting of three or four turns of wire placed about 12 inches from the internal aerial coils.

wire placed about 12 inches from the internal aerial coils.

M.W.—Switch receiver to 500m, feed in a 500m (600 kc/s) signal and adjust the core of L3 (B1) for maximum output. At the same frequency slide the internal aerial winding L2 (B1) along the ferrite rod for maximum output. Tune receiver to 200m, feed in a 200m (1.500 kc/s) signal and adjust C29 (F3) and C26 (G3) for maximum output.

L.W.—Switch receiver to 1,200m, feed in a 1,200m (250 kc/s) signal and adjust C30 (G3) and C25 (G3) for maximum output. Tune receiver to 1,800m, fed in a 1,800m (166.7 kc/s) signal and slide the internal aerial winding L1 (C1) along the ferrite rod for maximum output.



Sketch of the drive cord system as seen from the rear of the chassis with the gang at minimum capacitance.

#### VALVE ANALYSIS

Valve voltages and currents given in the table below are those derived from the manufacturers' information. They are the averages of readings taken on a number of receivers, which were operated from A.C. mains of 225V with their voltage adjustments set to the 225-250V tappings. The receivers were tuned to a point at the highest wavelength end of M.W. where there was no signal input.

Voltages were measured on the 10V and 400V ranges of a Model 7 Avometer, chassis being the negative connection. The voltage measured across C23 was 265V, and across C16 was 75V. The voltage measured between chassis and the junction of R18 and b44 filament was 6V, and between chassis and the junction of R18 and S5(M) was 85V. The total H.T. current was 12mA. Valve voltages and currents given in the table

Valve	An	ode	Se	reen
valive	v	mA	v	mA
V1 1R5	80	1.1	50	1.4
V2 1T4 V3 1S5	85 15	1.6	60 10	0.03
V4 3V4	82	6.0	85	1.2

#### **GENERAL NOTES**

Switches.—\$1-\$3 are the waveband switches and \$4(B)-\$10(B) are the mains/battery changeover switches ganged in two rotary units on the
chassis deck. These units are indicated in our
plan illustration of the chassis and shown in
detail in the diagram in column 3, where they
are drawn as seen from the rear of an upright
chassis. \$1 closes for M.W. operation, and
\$2, \$3 close for L.W. operation, and
\$2, \$3 close for L.W. operation, and
\$3(B), \$6(B),
and \$7(B) \$10(B) all close for battery operation as indicated by the suffix (B) and \$5(M),
\$8(M) and \$9(M) close for mains operation.
All the switches open in the "off" position.

Batteries.—The batteries recommended by the
manufacturers are as follows: H.T., Ever-Ready
B138 or Vidor L55536, rated at 90V; L.T., EverReady AD42 or Vidor L5558, rated at 7.5V.

Drive Cord Replacement.—About 3ft of nylonbraided glass yarn is required for a new drive
cord. It should be run as indicated in the Switches .- S1-S3 are the waveband switches

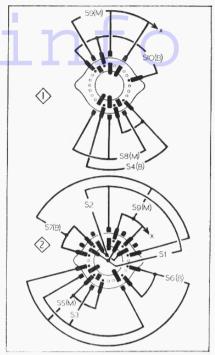


Diagram of the waveband and mains/battery switch units. S9(M) consists of two switches in series, one on each unit, the common connection between them being indicated by the arrow labelled x on each

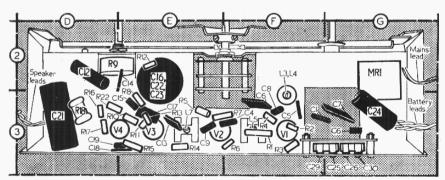
sketch of the drive cord system (col. 1), where it is viewed from the rear of the chassis with the gang at minimum capacitance.

Dismartling.—To gain access to the chassis, the two captive bolts securing two rubber feet to the rear edge of the carrying case base cover should be unscrewed, and the base cover slid off. The chassis can then be released by removing the four 4BA nuts securing the ends of the scale backing plate assembly to the carrying case. ing case.

Ing case:

Modifications.—To improve the quality of reproduction, later versions of the receiver on which this service sheet was prepared incorporate the following modifications. The bias on V4, which was originally made higher than normal in the interests of H.T. battery economy, is reduced by short-circuiting R22. The screen of V4 is connected to the H.T. positive line instead of to the junction of R12 and R13.

In earlier models an additional switch, which closed for mains operation, was connected in the lead between S4(B), V4 filament and R18. An additional switch, which closed for battery operation, was also connected in series with the lead from the L.T. positive plug and S4(B). A Hopf capacitor was also connected across L1.



Underside view of the chassis. All the R.F. and oscillator adjustments are identified in locations B1, F3 and G3.